

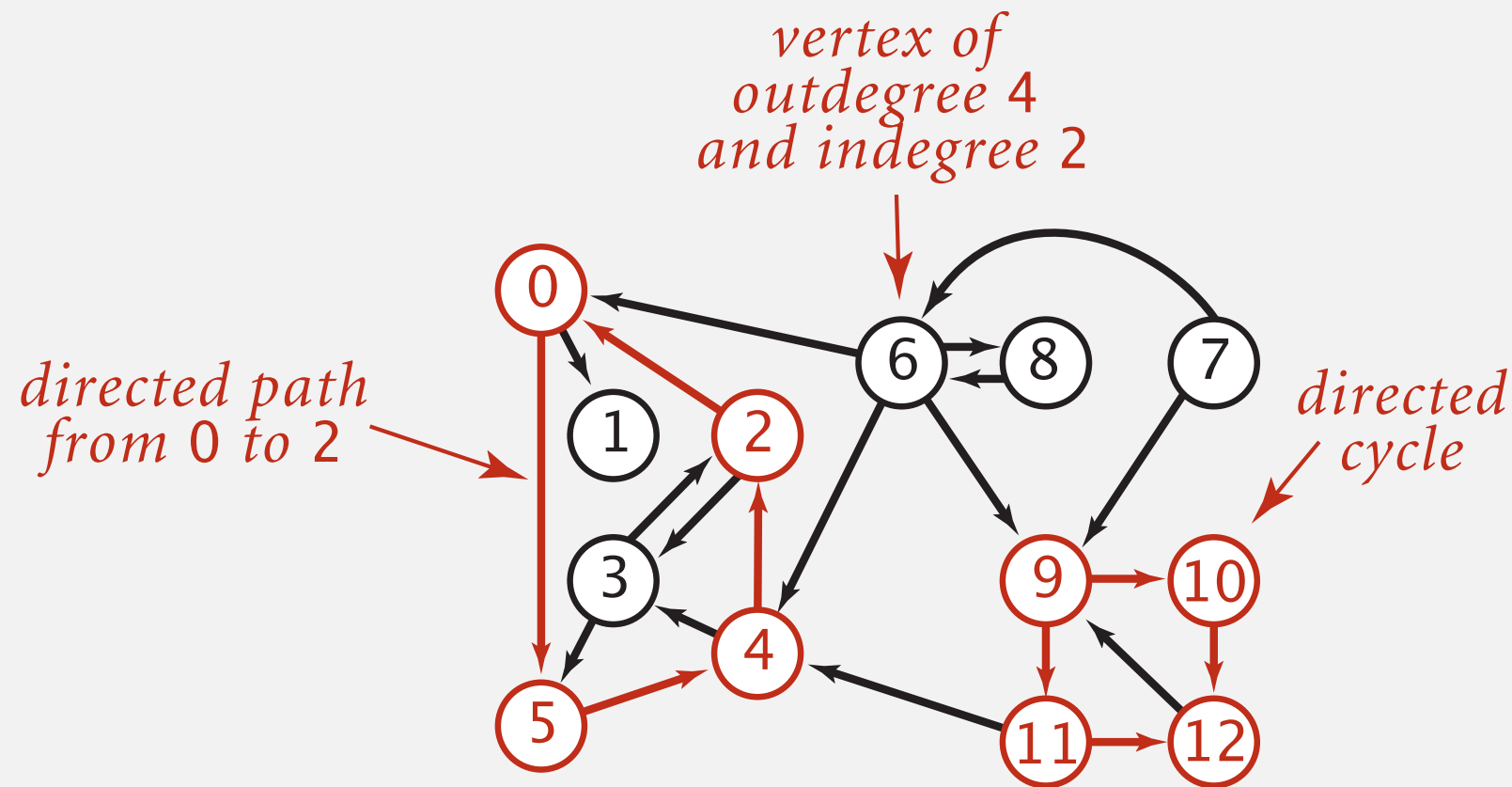
## 4.2 DIRECTED GRAPHS



- ▶ digraph API
- ▶ digraph search
- ▶ topological sort
- ▶ strong components

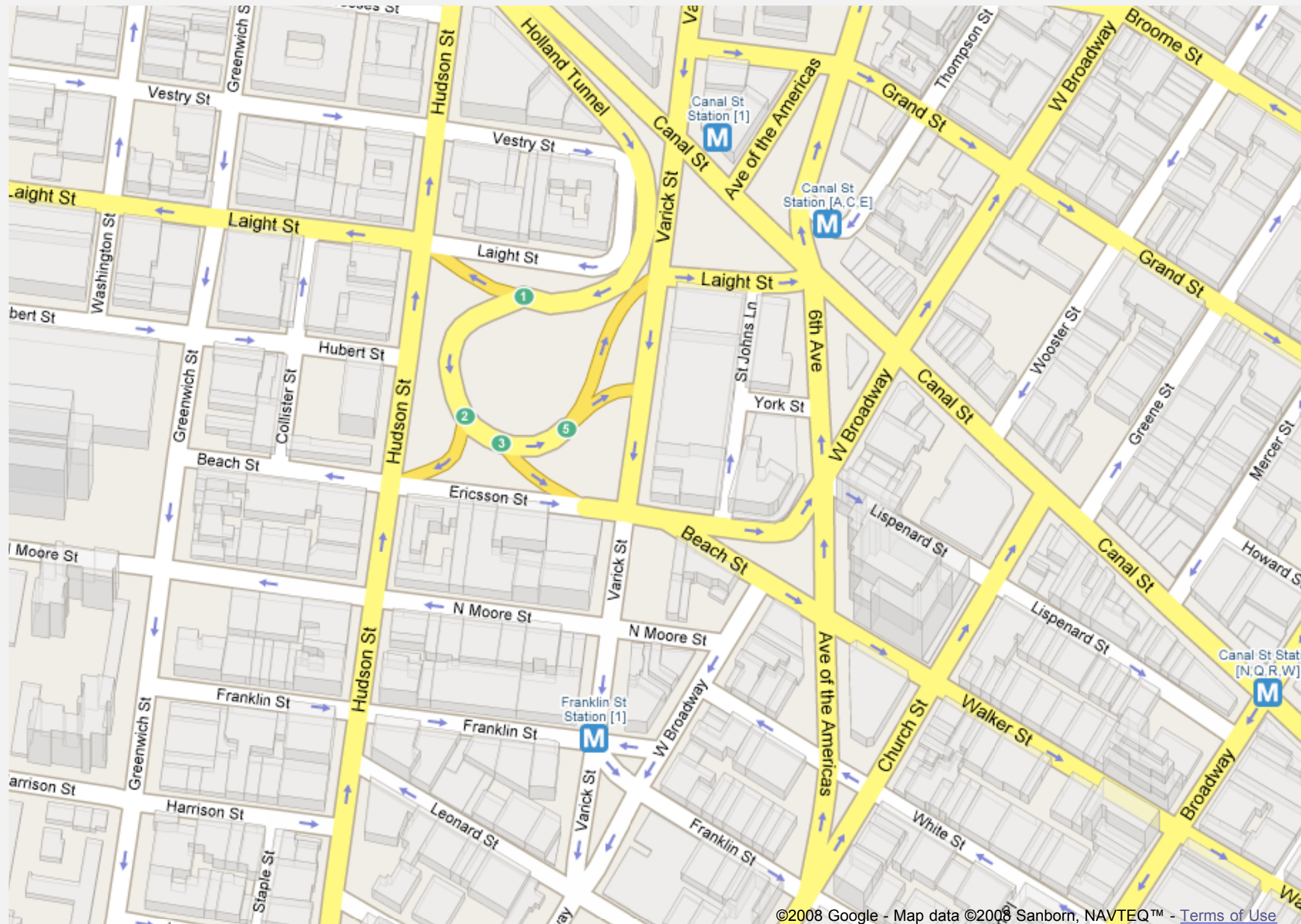
# Directed graphs

**Digraph.** Set of vertices connected pairwise by **directed** edges.



# Road network

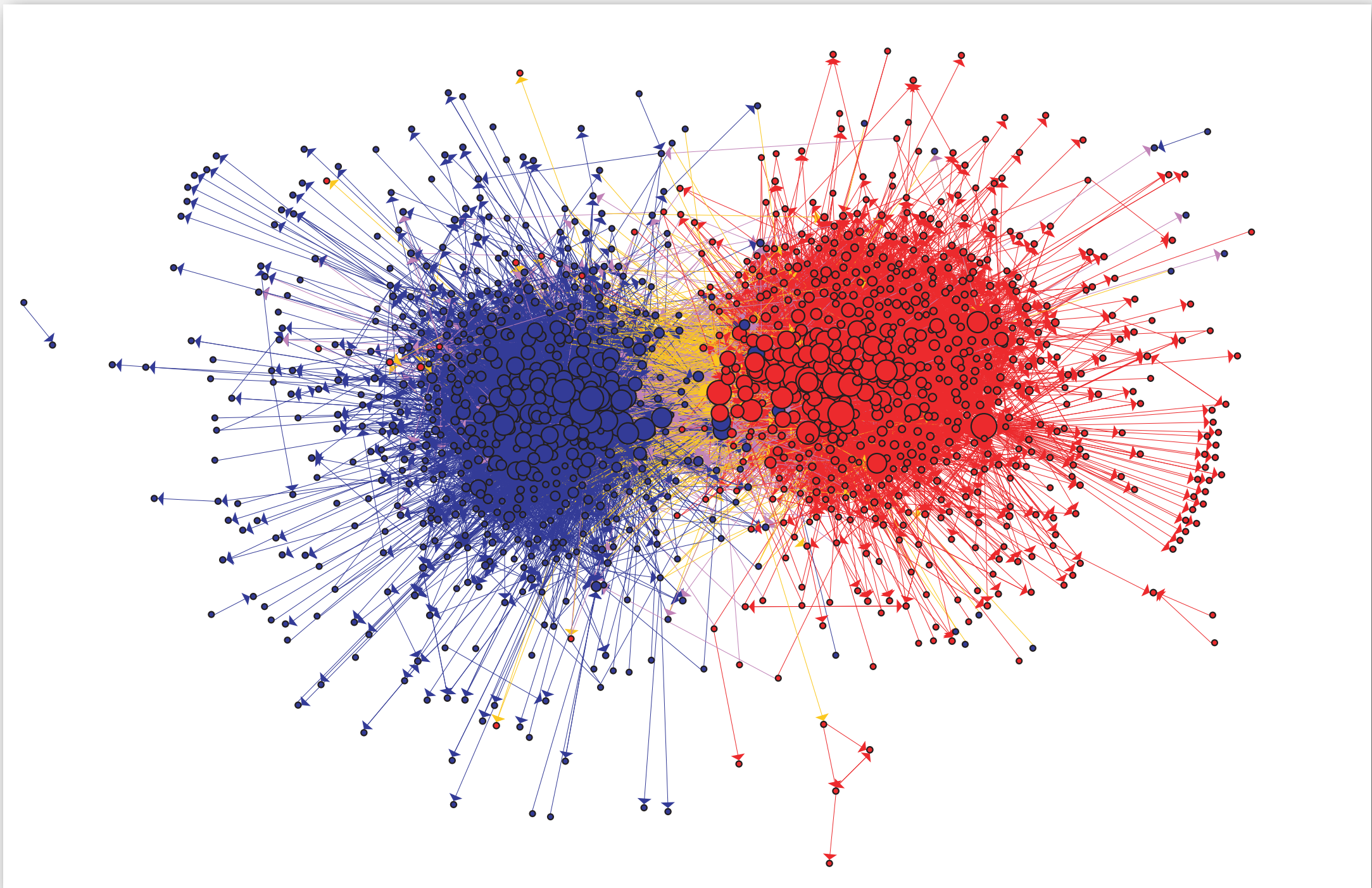
Vertex = intersection; edge = one-way street.





# Political blogosphere graph

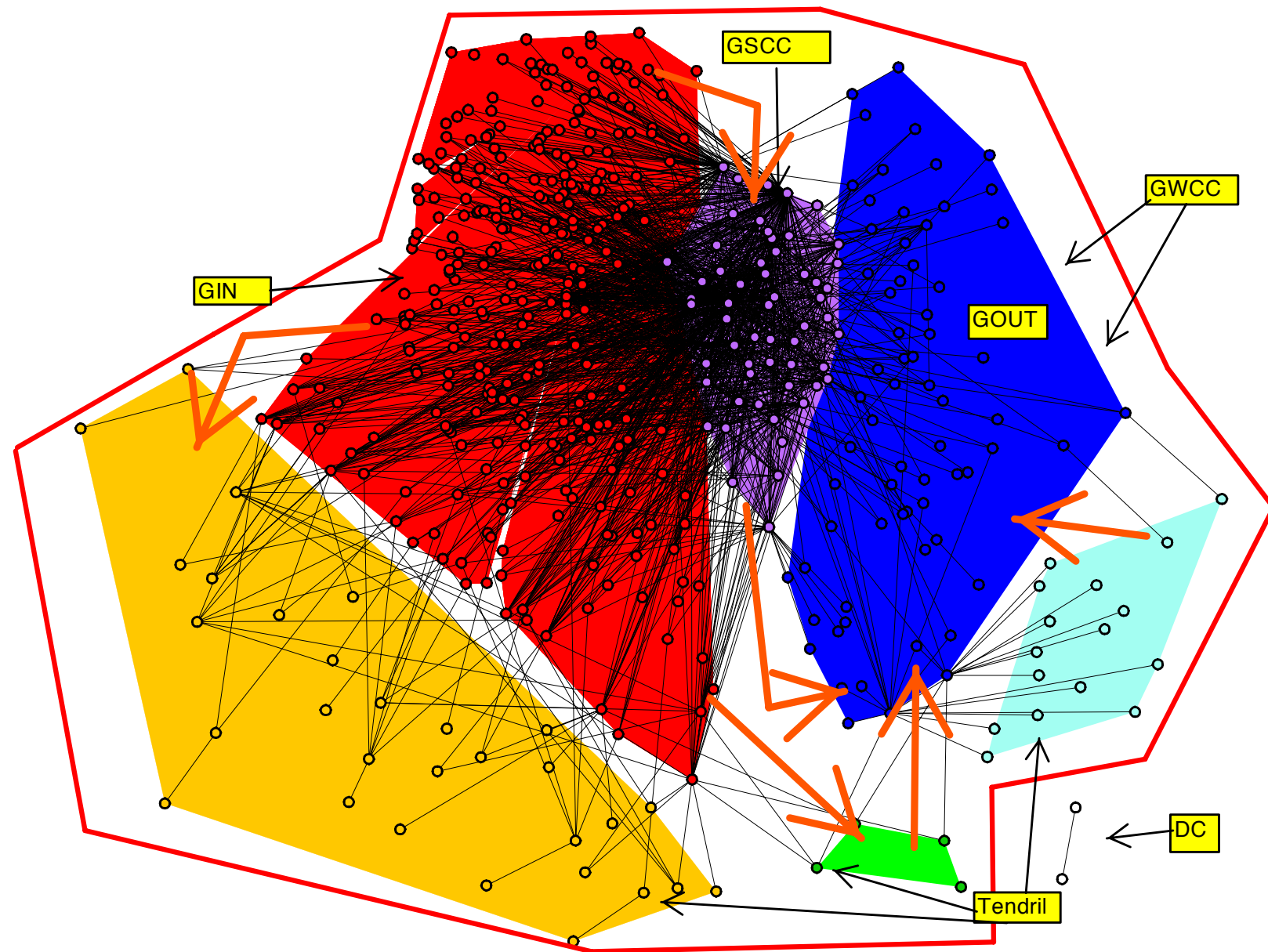
Vertex = political blog; edge = link.



The Political Blogosphere and the 2004 U.S. Election: Divided They Blog, Adamic and Glance, 2005

# Overnight interbank loan graph

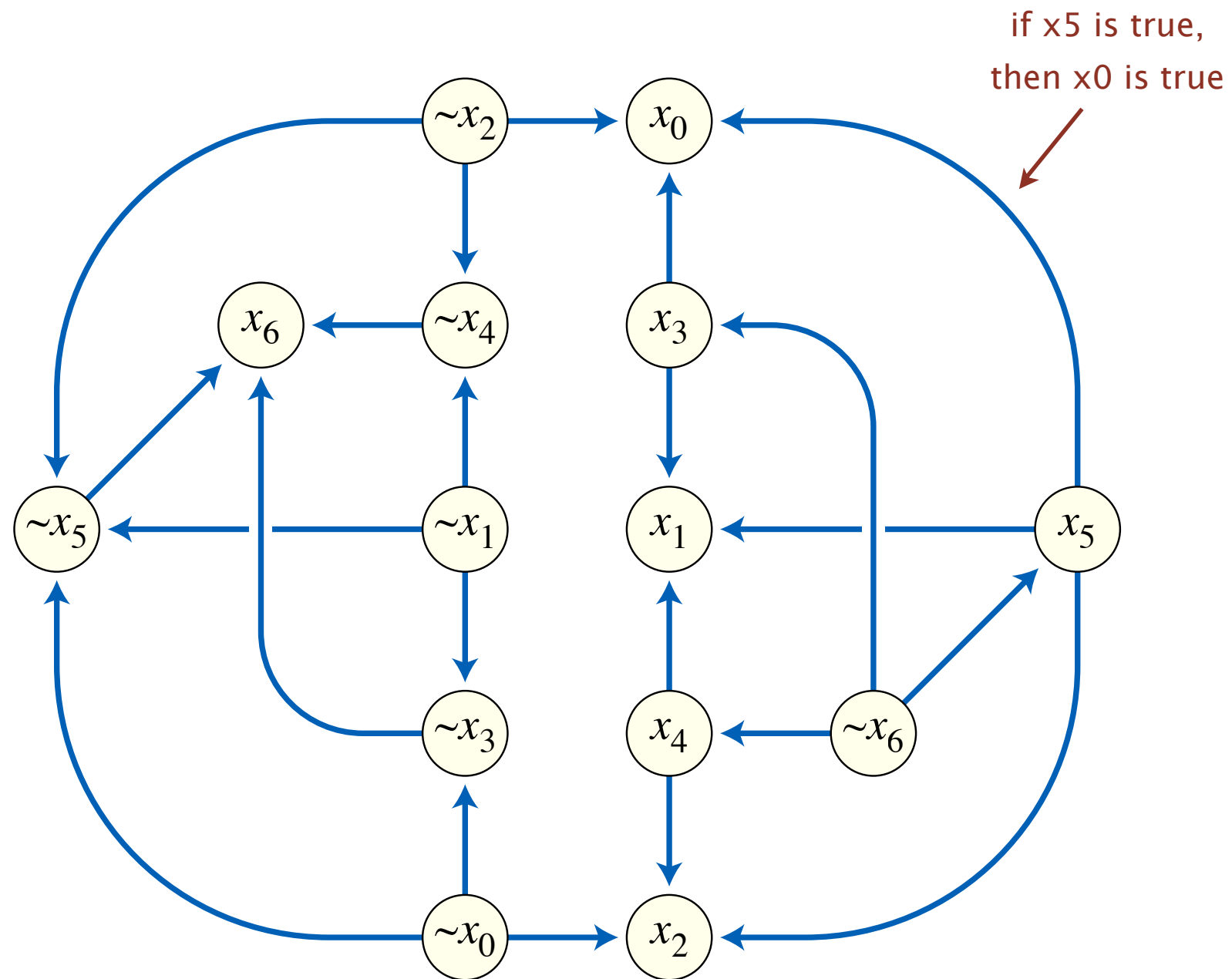
Vertex = bank; edge = overnight loan.



The Topology of the Federal Funds Market, Bech and Atalay, 2008

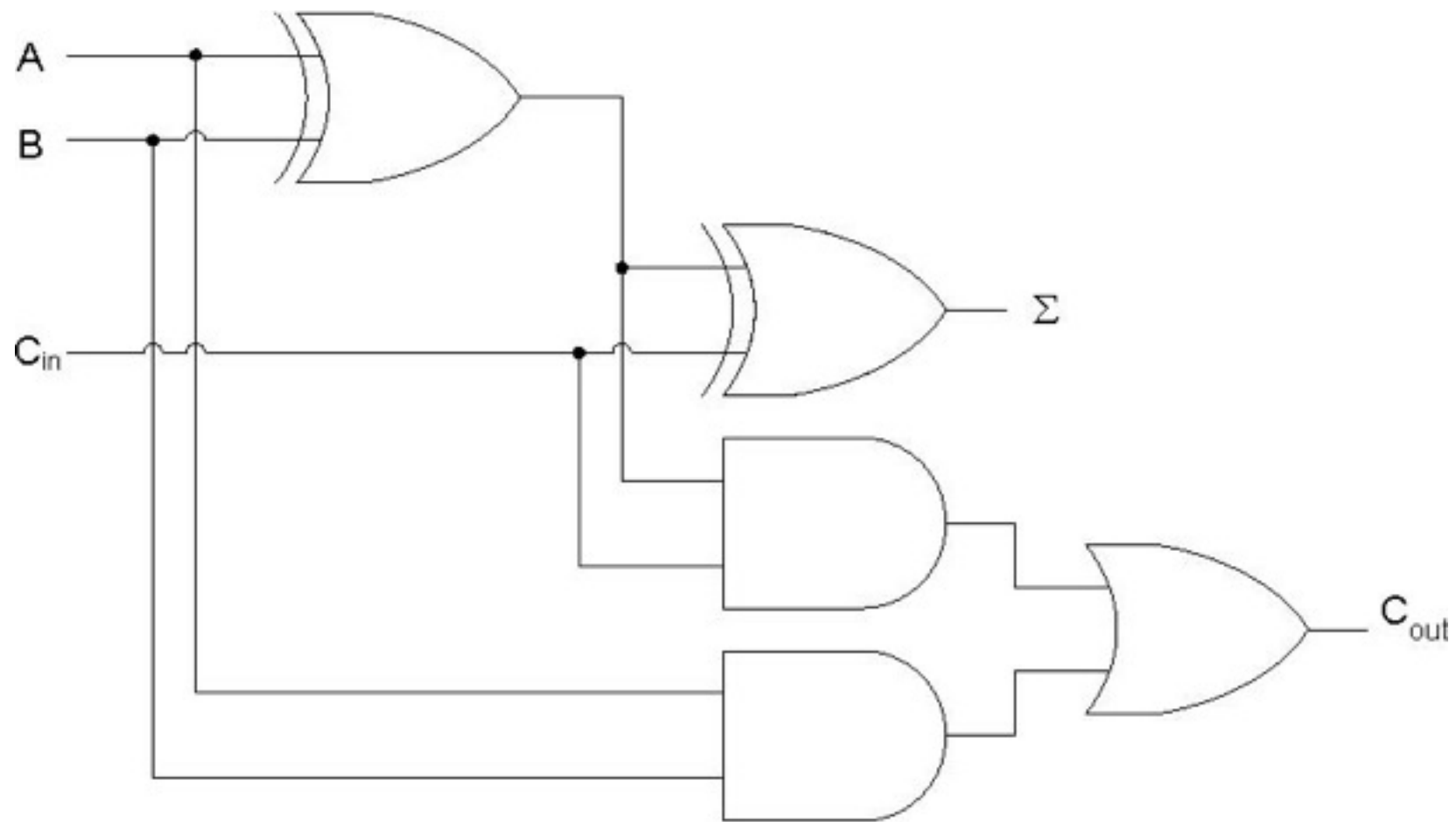
# Implication graph

Vertex = variable; edge = logical implication.



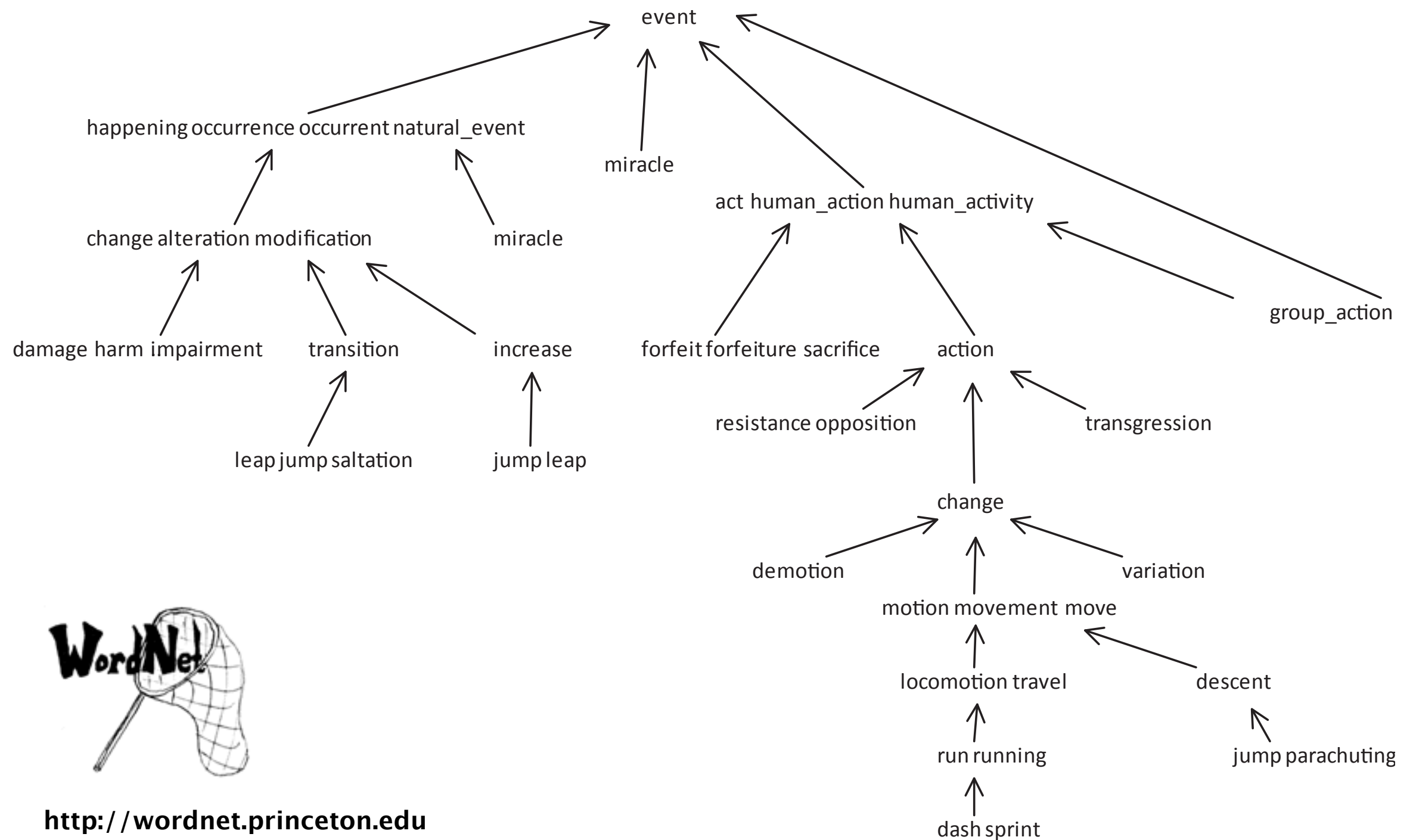
# Combinational circuit

Vertex = logical gate; edge = wire.



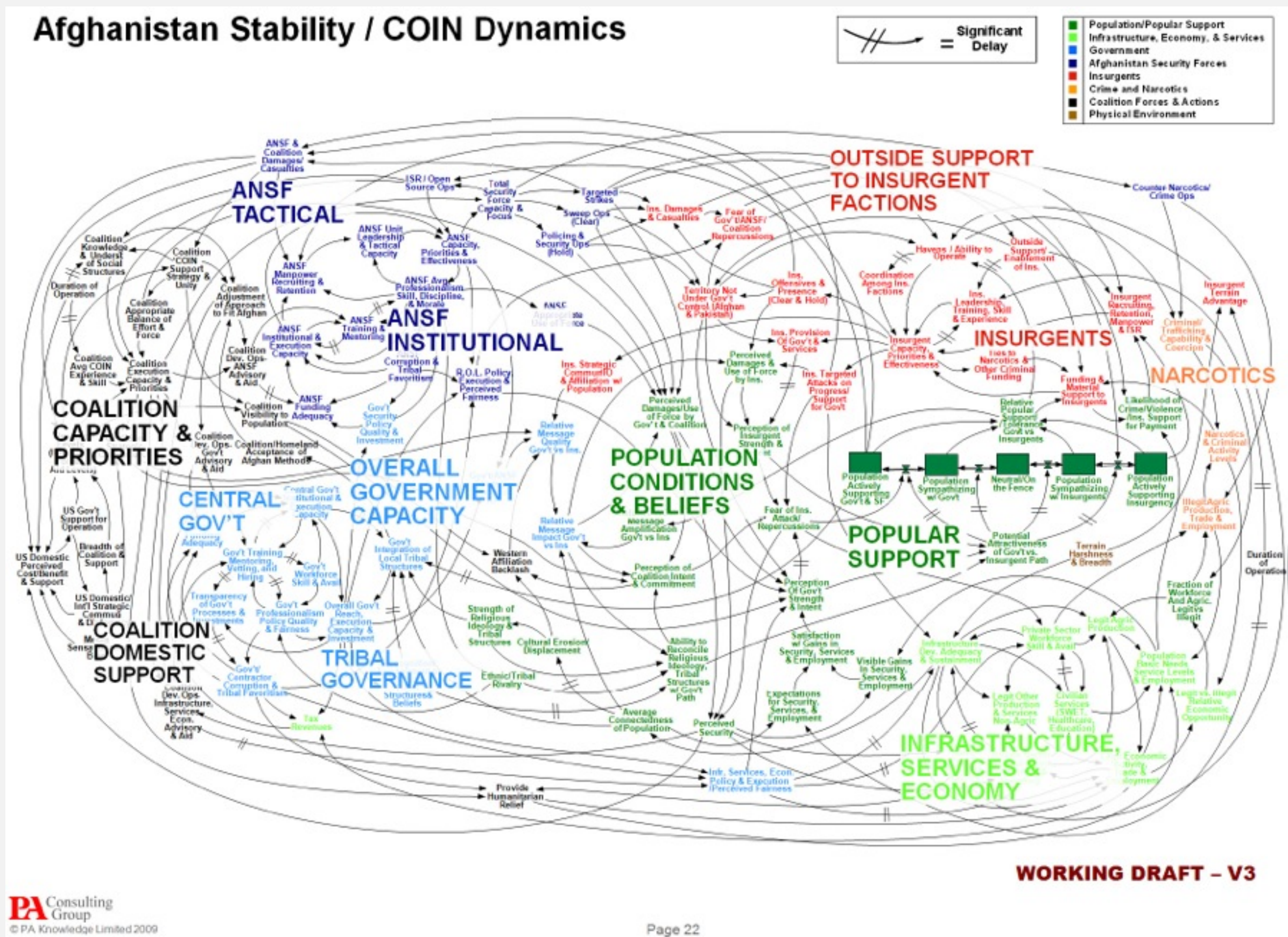
# WordNet graph

Vertex = synset; edge = hypernym relationship.





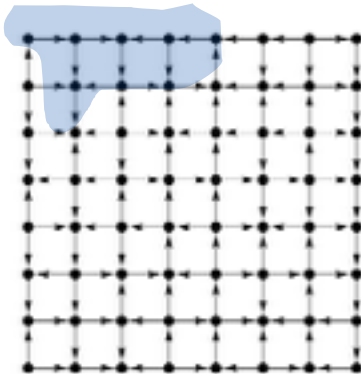
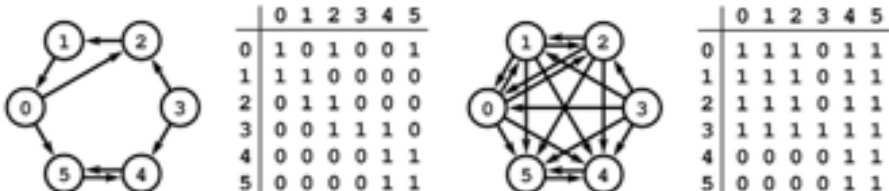
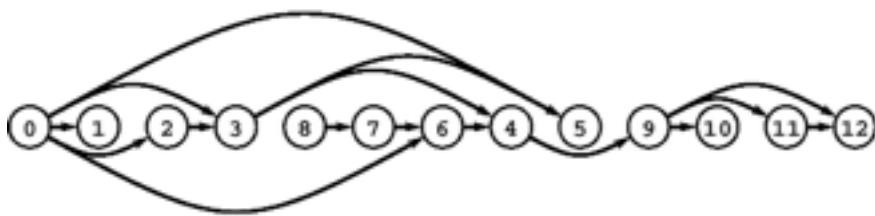
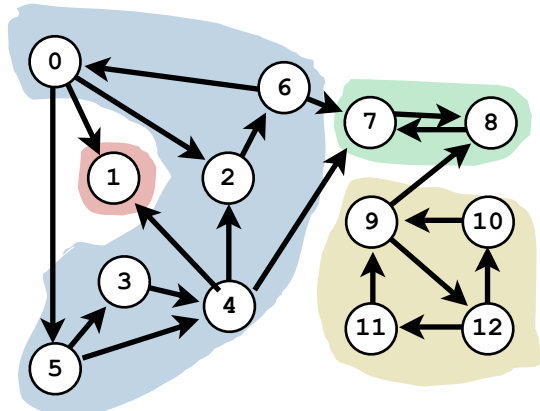
# The McChrystal Afghanistan PowerPoint slide



# Digraph applications

digraph	vertex	directed edge
transportation	street intersection	one-way street
web	web page	hyperlink
food web	species	predator-prey relationship
WordNet	synset	hypernym
scheduling	task	precedence constraint
financial	bank	transaction
cell phone	person	placed call
infectious disease	person	infection
game	board position	legal move
citation	journal article	citation
object graph	object	pointer
inheritance hierarchy	class	inherits from
control flow	code block	jump

# Digraph-processing: algorithms of the day

single-source reachability		DFS																																																																																																		
transitive closure	 <table border="1" data-bbox="1174 784 1372 974"><thead><tr><th></th><th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th></tr></thead><tbody><tr><th>0</th><td>1</td><td>0</td><td>1</td><td>0</td><td>0</td><td>1</td></tr><tr><th>1</th><td>1</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td></tr><tr><th>2</th><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>0</td></tr><tr><th>3</th><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td></tr><tr><th>4</th><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><th>5</th><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr></tbody></table> <table border="1" data-bbox="1638 784 1835 974"><thead><tr><th></th><th>0</th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th></tr></thead><tbody><tr><th>0</th><td>1</td><td>1</td><td>1</td><td>0</td><td>1</td><td>1</td></tr><tr><th>1</th><td>1</td><td>1</td><td>1</td><td>0</td><td>1</td><td>1</td></tr><tr><th>2</th><td>1</td><td>1</td><td>1</td><td>0</td><td>1</td><td>1</td></tr><tr><th>3</th><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td></tr><tr><th>4</th><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><th>5</th><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr></tbody></table>		0	1	2	3	4	5	0	1	0	1	0	0	1	1	1	1	0	0	0	0	2	0	1	1	0	0	0	3	0	0	1	1	1	0	4	0	0	0	0	1	1	5	0	0	0	0	1	1		0	1	2	3	4	5	0	1	1	1	0	1	1	1	1	1	1	0	1	1	2	1	1	1	0	1	1	3	1	1	1	1	1	1	4	0	0	0	0	1	1	5	0	0	0	0	1	1	DFS (from each vertex)
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topological sort (DAG)		DFS																																																																																																		
strong components		Kosaraju DFS (twice)																																																																																																		

- ▶ **digraph API**
- ▶ digraph search
- ▶ topological sort
- ▶ strong components



# Digraph API

```
public class Digraph
```

```
    Digraph(int V)
```

*create an empty digraph with V vertices*

```
    Digraph(In in)
```

*create a digraph from input stream*

```
    void addEdge(int v, int w)
```

*add a directed edge  $v \rightarrow w$*

```
    Iterable<Integer> adj(int v)
```

*vertices pointing from v*

```
    int V()
```

*number of vertices*

```
    int E()
```

*number of edges*

```
    Digraph reverse()
```

*reverse of this digraph*

```
    String toString()
```

*string representation*

```
In in = new In(args[0]);  
Digraph G = new Digraph(in);
```

*read digraph from  
input stream*

```
for (int v = 0; v < G.V(); v++)  
    for (int w : G.adj(v))  
        StdOut.println(v + "->" + w);
```

*print out each  
edge (once)*

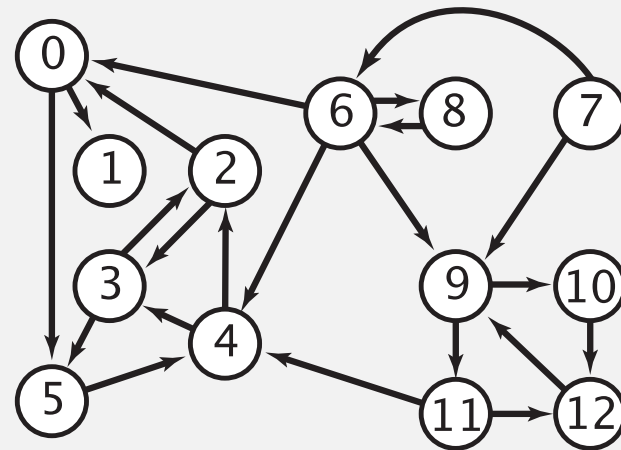


# Digraph API

**tinyDG.txt**

*V* → 13  
22 ← *E*

```
4 2
2 3
3 2
6 0
0 1
2 0
11 12
12 9
9 10
9 11
7 9
10 12
11 4
4 3
3 5
6 8
8 6
:
```



```
% java Digraph tinyDG.txt
0->5
0->1
2->0
2->3
3->5
3->2
4->3
4->2
5->4
:
11->4
11->12
12-9
```

```
In in = new In(args[0]);
Digraph G = new Digraph(in);

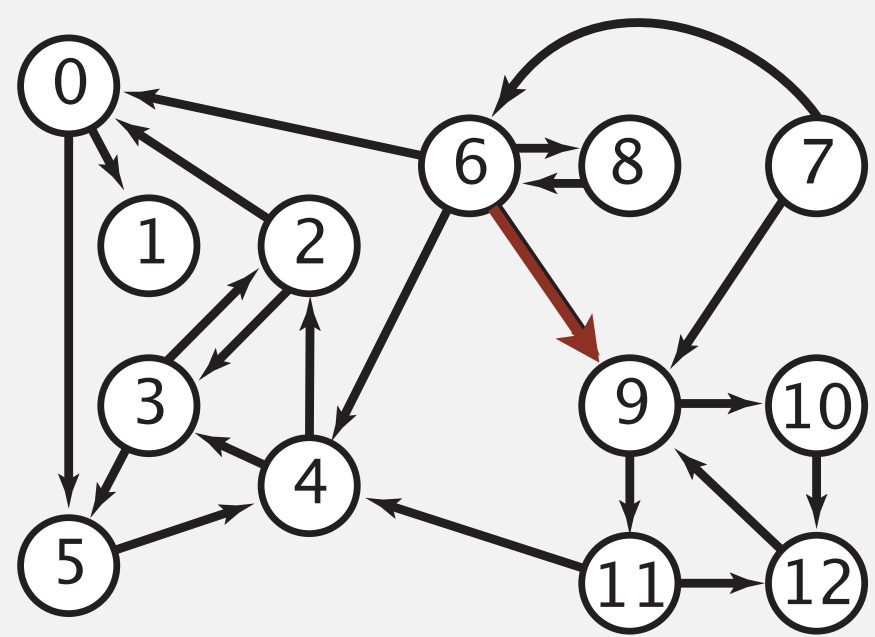
for (int v = 0; v < G.V(); v++)
    for (int w : G.adj(v))
        StdOut.println(v + "->" + w);
```

← read digraph from  
input stream

← print out each  
edge (once)

# Set-of-edges digraph representation

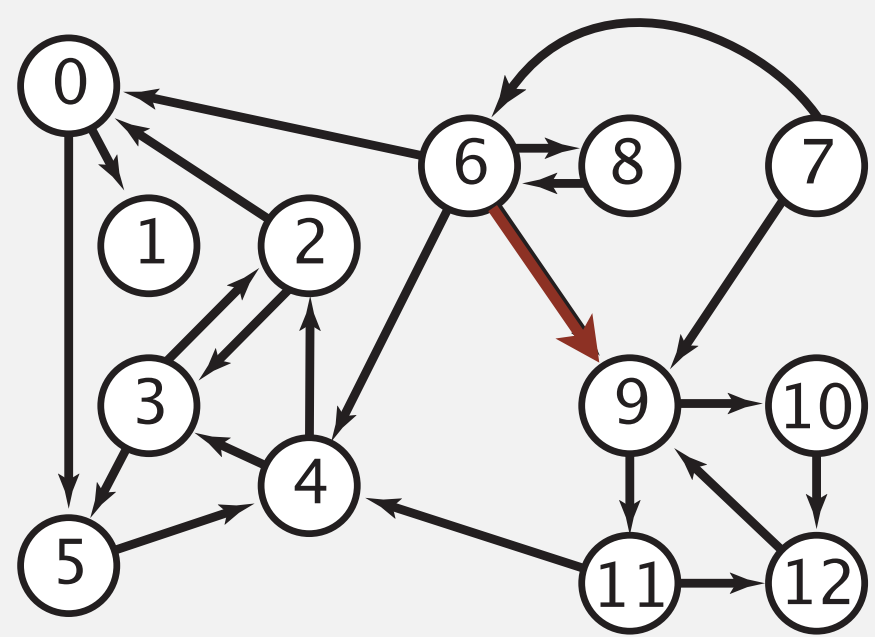
Store a list of the edges (linked list or array).



0	1
0	5
2	0
2	3
3	2
3	5
4	2
4	3
5	4
6	0
6	4
6	8
6	9
7	6
7	9
8	6
9	10
9	11
10	12
11	4
11	12
12	9

# Adjacency-matrix digraph representation

Maintain a two-dimensional  $v$ -by- $v$  boolean array;  
for each edge  $v \rightarrow w$  in the digraph: `adj[v][w] = true`.

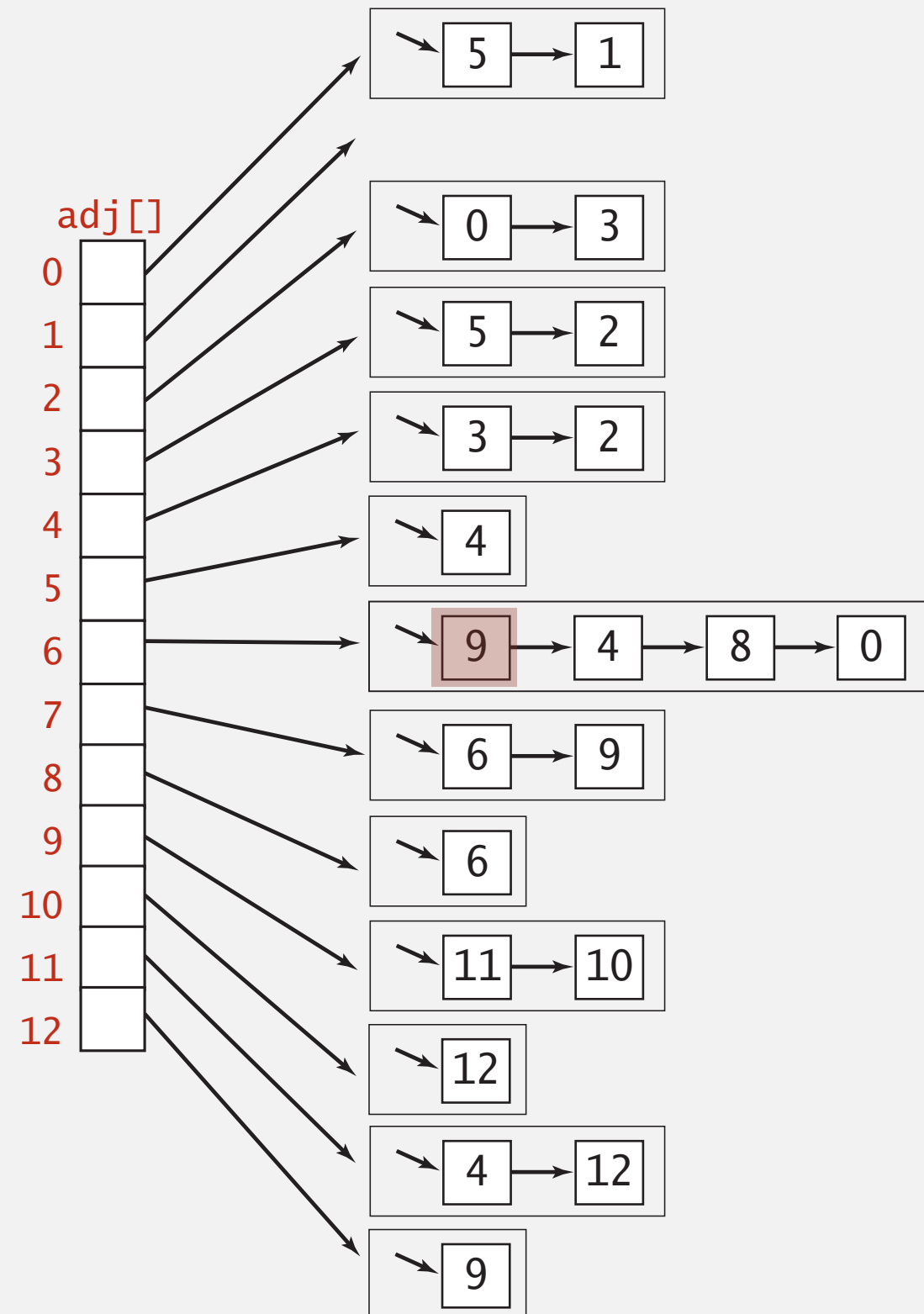
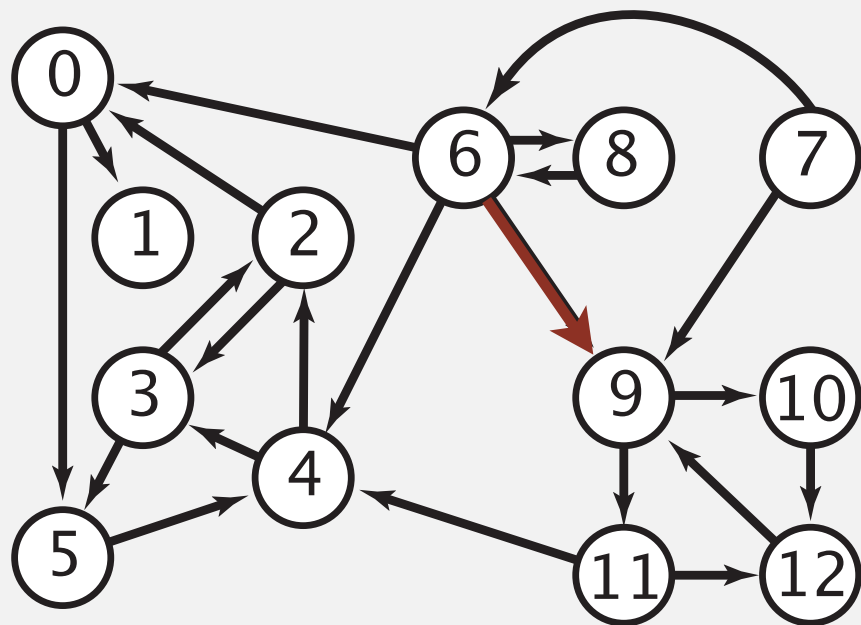


		to												
		0	1	2	3	4	5	6	7	8	9	10	11	12
from	0	0	1	0	0	0	1	0	0	0	0	0	0	0
	1	0	0	0	0	0	0	0	0	0	0	0	0	0
	2	1	0	0	1	0	0	0	0	0	0	0	0	0
	3	0	0	1	0	0	1	0	0	0	0	0	0	0
	4	0	0	1	1	0	0	0	0	0	0	0	0	0
	5	0	0	0	0	1	0	0	0	0	0	0	0	0
	6	0	0	0	0	1	0	0	0	1	1	0	0	0
	7	0	0	0	0	0	0	1	0	0	1	0	0	0
	8	0	0	0	0	0	0	1	0	0	0	0	0	0
	9	0	0	0	0	0	0	0	0	0	0	1	1	0
	10	0	0	0	0	0	0	0	0	0	0	0	0	1
	11	0	0	0	0	1	0	0	0	0	0	0	0	1
	12	0	0	0	0	0	0	0	0	0	1	0	0	0

Note: parallel edges disallowed

# Adjacency-lists digraph representation

Maintain vertex-indexed array of lists.



# Adjacency-lists graph representation: Java implementation

```
public class Graph
{
```

```
    private final int V;
```

```
    private final Bag<Integer>[] adj;
```

← adjacency lists

```
    public Graph(int V)
```

```
    {
```

```
        this.V = V;
```

```
        adj = (Bag<Integer>[]) new Bag[V];
```

```
        for (int v = 0; v < V; v++)
```

```
            adj[v] = new Bag<Integer>();
```

```
    }
```

← create empty graph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {
```

```
        adj[v].add(w);
```

```
        adj[w].add(v);
```

```
    }
```

← add edge v-w

```
    public Iterable<Integer> adj(int v)
```

```
    {    return adj[v];    }
```

```
}
```

← iterator for vertices  
adjacent to v



# Adjacency-lists digraph representation: Java implementation

```
public class Digraph
{
```

```
    private final int V;
```

```
    private final Bag<Integer>[] adj;
```

← adjacency lists

```
    public Digraph(int V)
```

```
    {
```

```
        this.V = V;
```

```
        adj = (Bag<Integer>[]) new Bag[V];
```

```
        for (int v = 0; v < V; v++)
```

```
            adj[v] = new Bag<Integer>();
```

```
    }
```

← create empty digraph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {
```

```
        adj[v].add(w);
```

```
    }
```

← add edge  $v \rightarrow w$

```
    public Iterable<Integer> adj(int v)
```

```
    {    return adj[v];    }
```

```
}
```

← iterator for vertices  
pointing from v

# Digraph representations

**In practice.** Use adjacency-lists representation.

- Algorithms based on iterating over vertices pointing from  $v$ .
- Real-world digraphs tend to be sparse.

↖ huge number of vertices,  
small average vertex degree

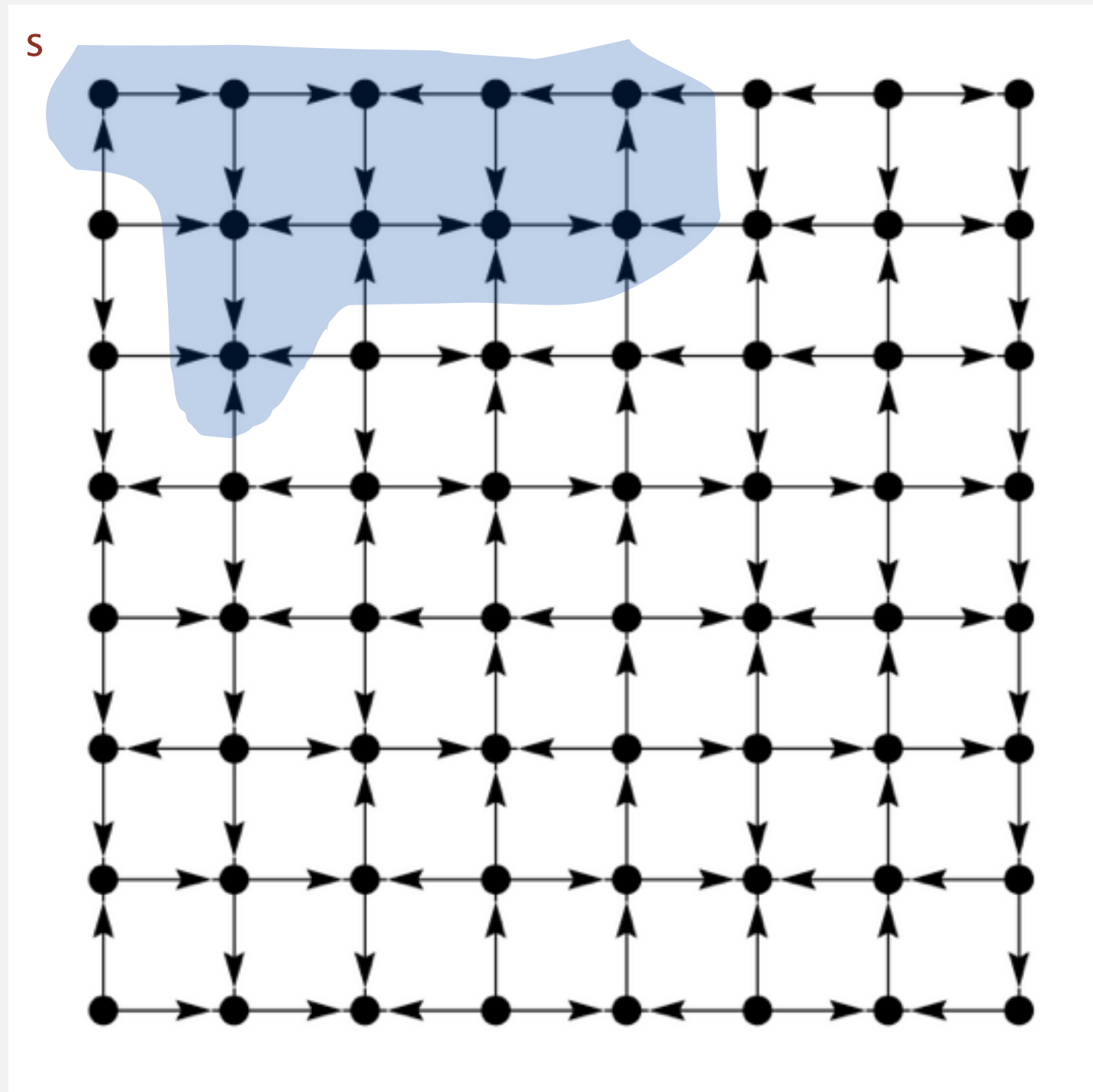
representation	space	insert edge from $v$ to $w$	edge from $v$ to $w$ ?	iterate over vertices pointing from $v$ ?
list of edges	$E$	1	$E$	$E$
adjacency matrix	$V$	1	1	$V$
adjacency lists	$E + V$	1	$\text{outdegree}(v)$	$\text{outdegree}(v)$

† disallows parallel edges

- ▶ digraph API
- ▶ **digraph search**
- ▶ topological sort
- ▶ strong components

# Reachability

**Problem.** Find all vertices reachable from  $s$  along a directed path.



# Depth-first search in digraphs

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- DFS is a **digraph** algorithm.

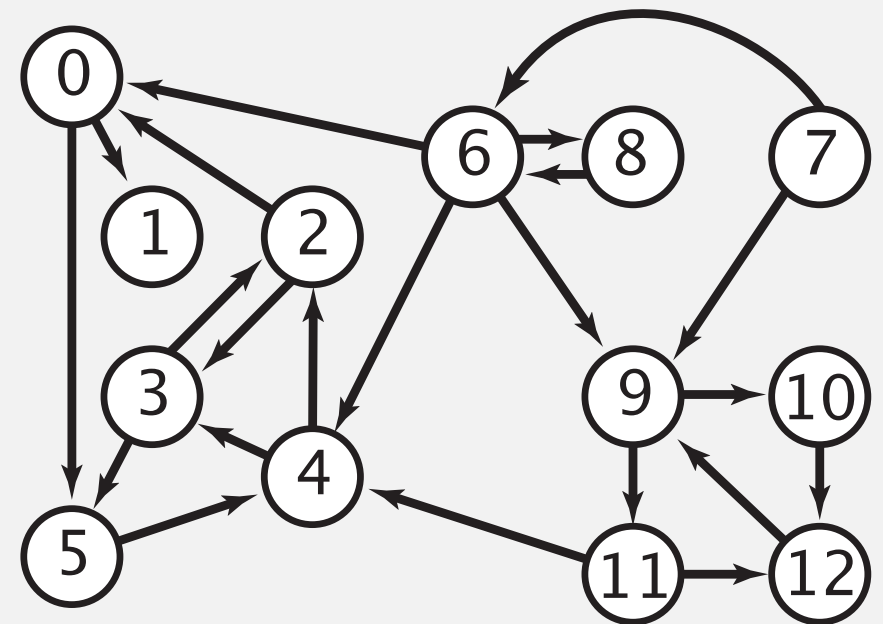
**DFS** (to visit a vertex  $v$ )

---

Mark  $v$  as visited.

Recursively visit all unmarked  
vertices  $w$  pointing from  $v$ .

---



- See [Depth-first search in digraphs demo](#)



# Depth-first search (in undirected graphs)

Recall code for **undirected** graphs.

```
public class DepthFirstSearch  
{
```

```
    private boolean[] marked;
```

← true if path to s

```
    public DepthFirstSearch(Graph G, int s)
```

```
    {
```

```
        marked = new boolean[G.V()];
```

← constructor marks  
vertices connected to s

```
        dfs(G, s);
```

```
    }
```

```
    private void dfs(Graph G, int v)
```

```
    {
```

```
        marked[v] = true;
```

```
        for (int w : G.adj(v))
```

```
            if (!marked[w]) dfs(G, w);
```

← recursive DFS does the work

```
    }
```

```
    public boolean visited(int v)
```

```
    { return marked[v]; }
```

← client can ask whether any  
vertex is connected to s

```
}
```

# Depth-first search (in directed graphs)

Code for **directed** graphs identical to undirected one.

[substitute `Digraph` for `Graph`]

```
public class DirectedDFS
{
```

```
    private boolean[] marked;
```

← true if path from s

```
    public DirectedDFS(Digraph G, int s)
```

```
    {
```

```
        marked = new boolean[G.V()];
```

← constructor marks  
vertices reachable from s

```
        dfs(G, s);
```

```
    }
```

```
    private void dfs(Digraph G, int v)
```

← recursive DFS does the work

```
    {
```

```
        marked[v] = true;
```

```
        for (int w : G.adj(v))
```

```
            if (!marked[w]) dfs(G, w);
```

```
    }
```

```
    public boolean visited(int v)
```

← client can ask whether any  
vertex is reachable from s

```
    { return marked[v]; }
```

```
}
```

# Reachability application: program control-flow analysis

Every program is a digraph.

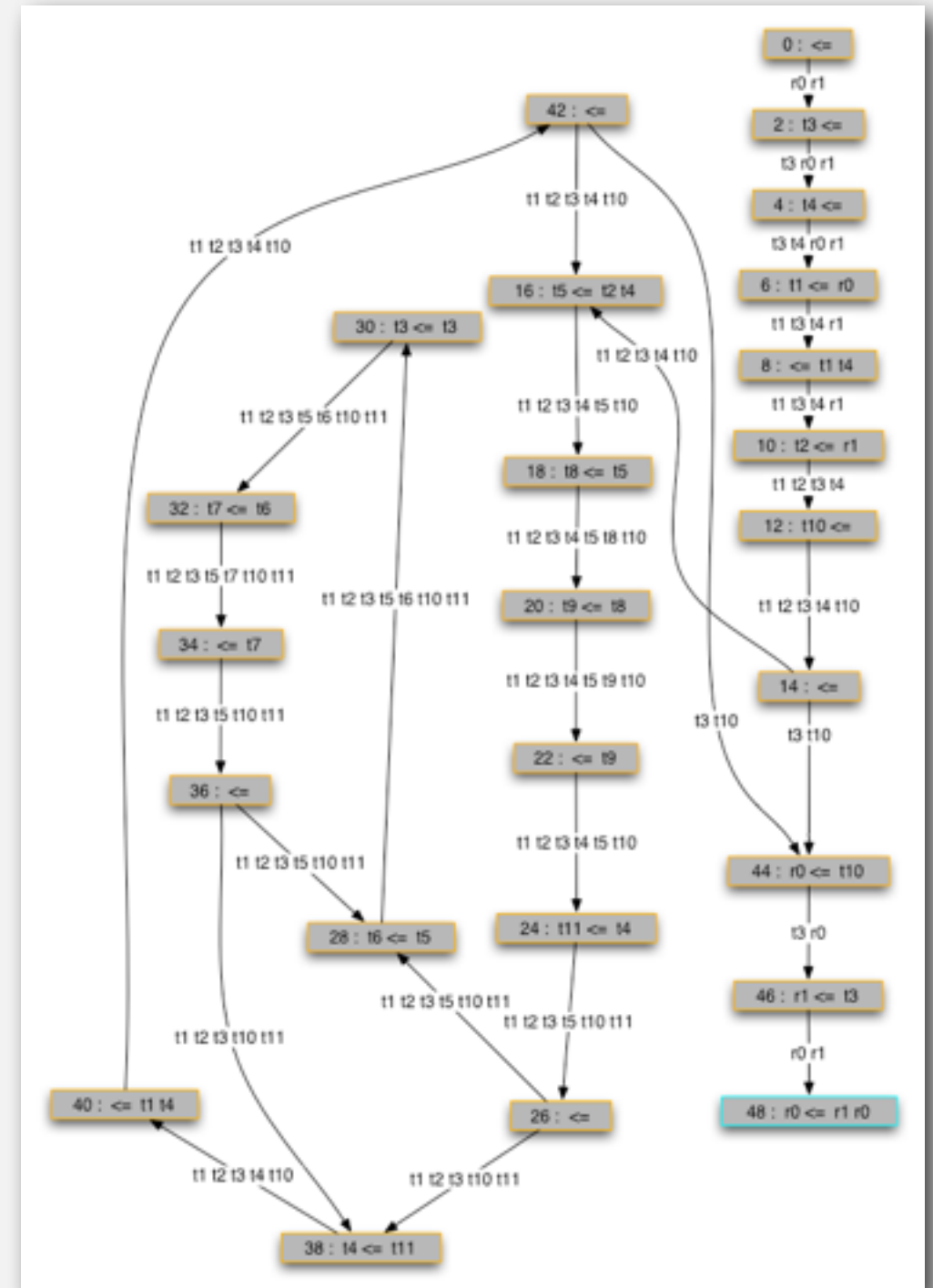
- Vertex = basic block of instructions (straight-line program).
- Edge = jump.

Dead-code elimination.

Find (and remove) unreachable code.

Infinite-loop detection.

Determine whether exit is unreachable.



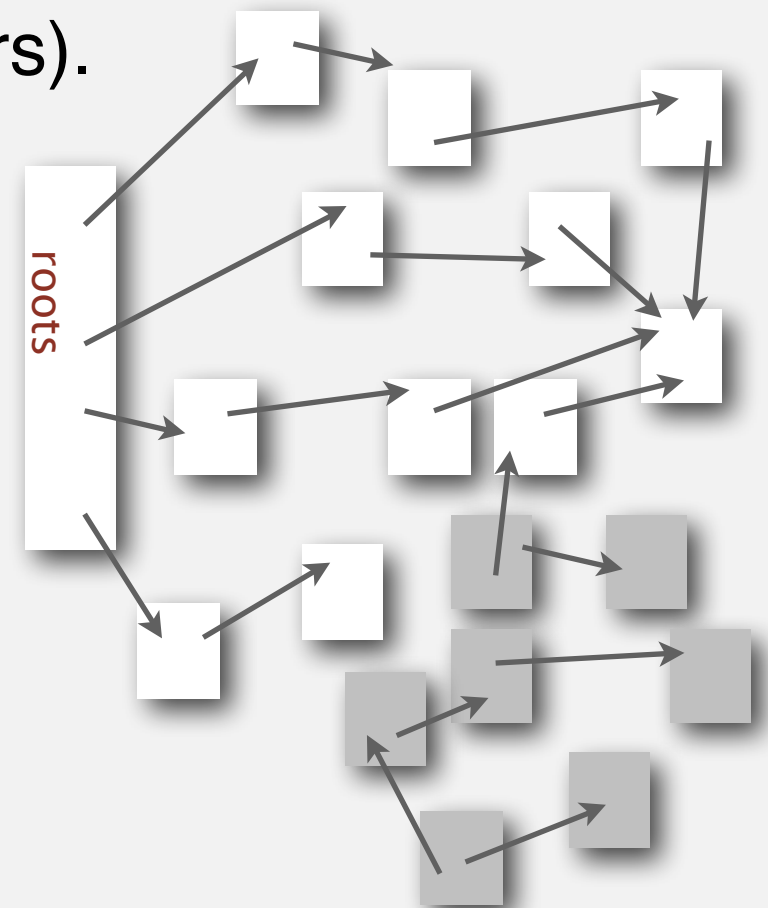
# Reachability application: mark-sweep garbage collector

Every data structure is a digraph.

- Vertex = object.
- Edge = reference.

**Roots.** Objects known to be directly accessible by program (e.g., stack).

**Reachable objects.** Objects indirectly accessible by program (starting at a root and following a chain of pointers).



# Depth-first search in digraphs summary

DFS enables direct solution of simple digraph problems.

- ✓ • Reachability.
- Path finding.
- Topological sort.
- Directed cycle detection.

Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly-connected components.

SIAM J. COMPUT.  
Vol. 1, No. 2, June 1972

## DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS\*

ROBERT TARJAN†

**Abstract.** The value of depth-first search or “backtracking” as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the strongly connected components of a directed graph and an algorithm for finding the biconnected components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by  $k_1V + k_2E + k_3$  for some constants  $k_1, k_2$ , and  $k_3$ , where  $V$  is the number of vertices and  $E$  is the number of edges of the graph being examined.



# Breadth-first search in digraphs

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a **digraph** algorithm.

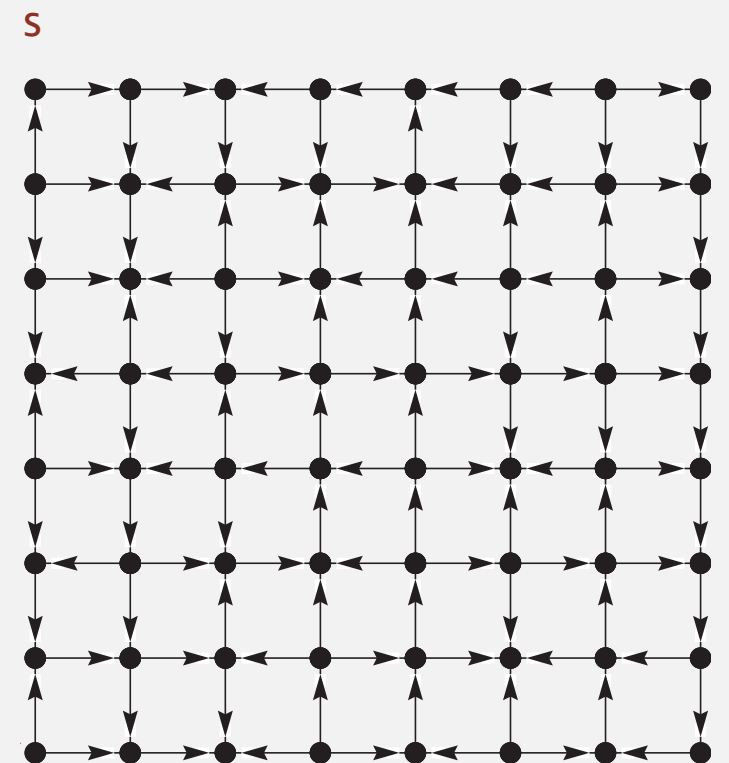
**BFS** (from source vertex  $s$ )

---

Put  $s$  onto a FIFO queue, and mark  $s$  as visited.

Repeat until the queue is empty:

- remove the least recently added vertex  $v$
  - for each unmarked vertex pointing from  $v$ :  
add to queue and mark as visited.
- 

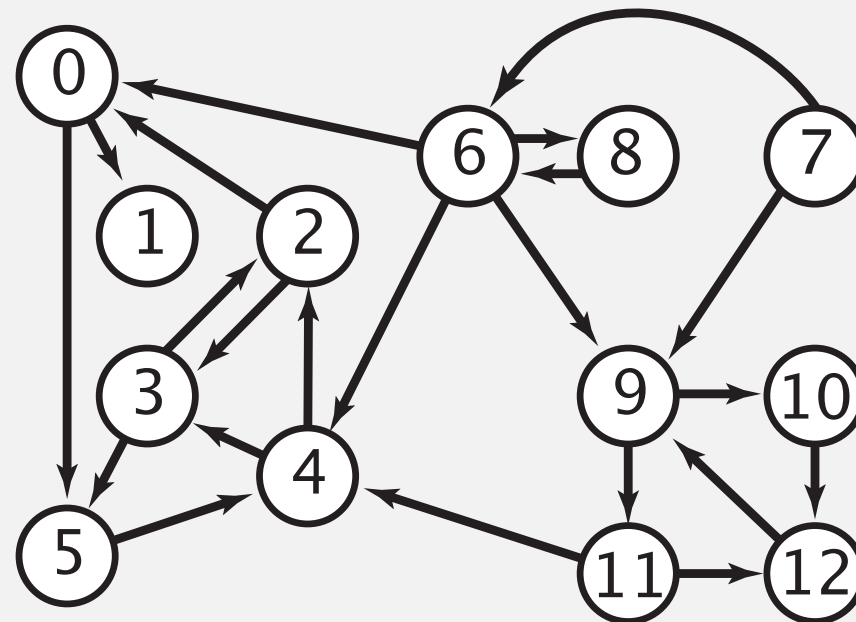


**Proposition.** BFS computes shortest paths (fewest number of edges).

# Multiple-source shortest paths

**Multiple-source shortest paths.** Given a digraph and a **set** of source vertices, find shortest path from any vertex in the set to each other vertex.

**Ex.** Shortest path from  $\{ 1, 7, 10 \}$  to 5 is  $7 \rightarrow 6 \rightarrow 4 \rightarrow 3 \rightarrow 5$ .



# Breadth-first search in digraphs application: web crawler

**Goal.** Crawl web, starting from some root web page, say

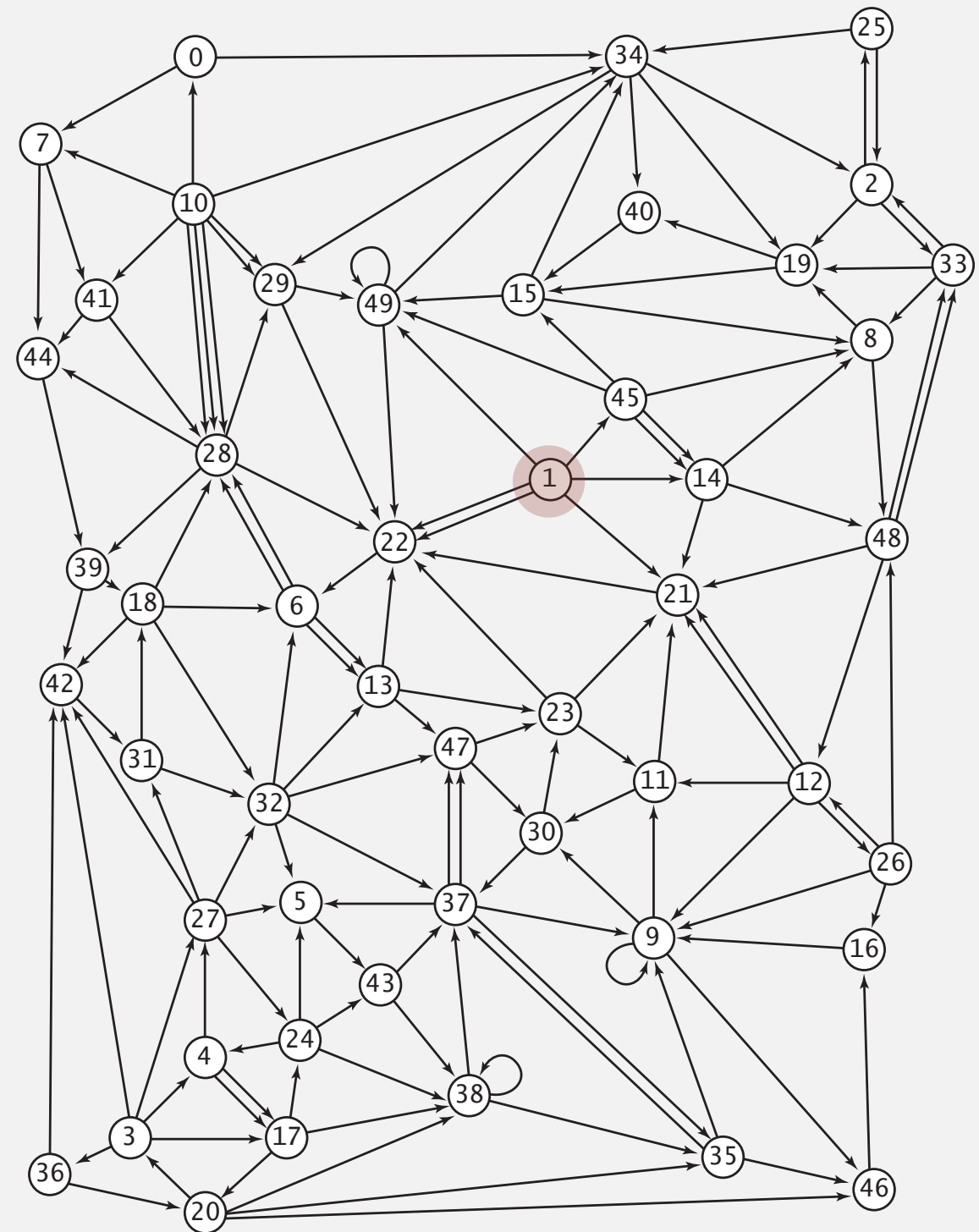
`www.princeton.edu`.

**Solution.** BFS with implicit graph.

**BFS.**

- Choose root web page as source  $s$ .
- Maintain a `queue` of websites to explore.
- Maintain a `set` of discovered websites.
- Dequeue the next website and enqueue websites to which it links (provided you haven't done so before).

**Q.** Why not use DFS?



# Bare-bones web crawler: Java implementation

```
Queue<String> queue = new Queue<String>();  
SET<String> discovered = new SET<String>();
```

← queue of websites to crawl  
← set of discovered websites

```
String root = "http://www.princeton.edu";  
queue.enqueue(root);  
discovered.add(root);
```

← start crawling from root website

```
while (!queue.isEmpty())  
{
```

```
    String v = queue.dequeue();  
    StdOut.println(v);  
    In in = new In(v);  
    String input = in.readAll();
```

← read in raw html from next  
website in queue

```
    String regexp = "http://(\\w+\\.)* (\\w+)";  
    Pattern pattern = Pattern.compile(regexp);  
    Matcher matcher = pattern.matcher(input);  
    while (matcher.find())  
    {
```

← use regular expression to find all URLs  
in website of form `http://xxx.yyy.zzz`  
[crude pattern misses relative URLs]

```
        String w = matcher.group();  
        if (!discovered.contains(w))  
        {  
            discovered.add(w);  
            queue.enqueue(w);  
        }
```

← if undiscovered, mark it as discovered  
and put on queue

```
    }  
}
```

- ▶ digraph API
- ▶ digraph search
- ▶ **topological sort**
- ▶ strong components

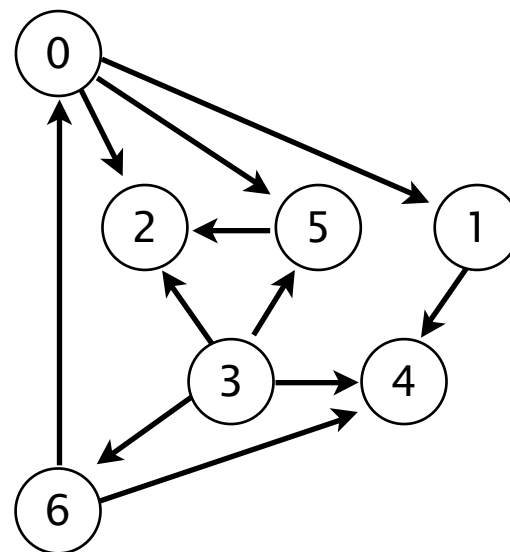
# Precedence scheduling

**Goal.** Given a set of tasks to be completed with precedence constraints,  
in which order should we schedule the tasks?

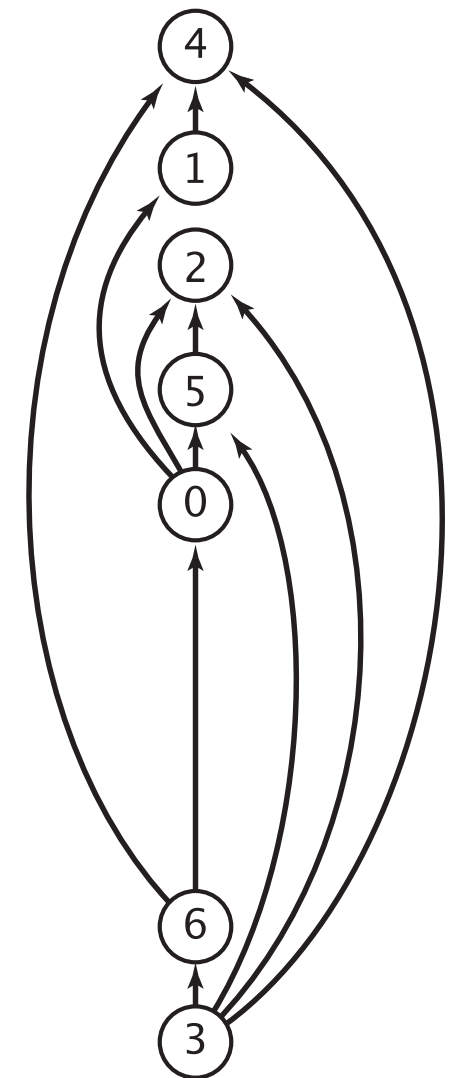
**Digraph model.** vertex = task; edge = precedence constraint

0. Algorithms
1. Complexity Theory
2. Artificial Intelligence
3. Intro to CS
4. Cryptography
5. Scientific Computing

tasks



precedence constraint graph



feasible schedule



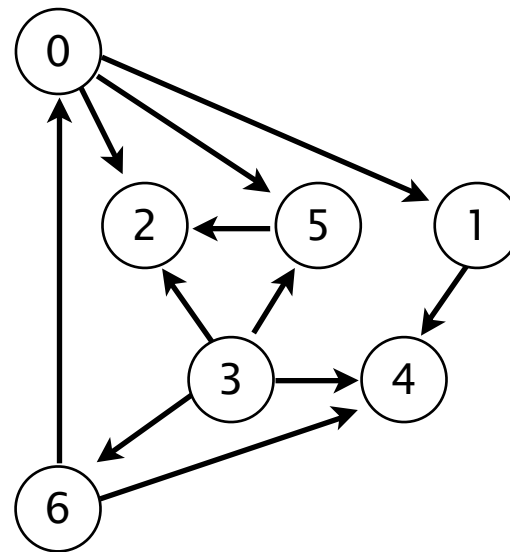
# Topological sort

DAG. Directed **acyclic** graph.

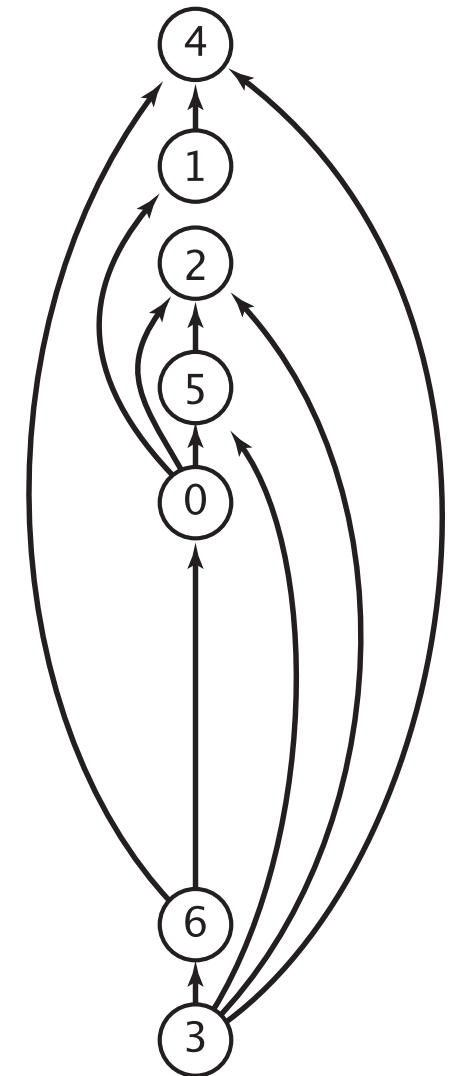
Topological sort. Redraw DAG so all edges point upwards.

$0 \rightarrow 5$	$0 \rightarrow 2$
$0 \rightarrow 1$	$3 \rightarrow 6$
$3 \rightarrow 5$	$3 \rightarrow 4$
$5 \rightarrow 4$	$6 \rightarrow 4$
$6 \rightarrow 0$	$3 \rightarrow 2$
$1 \rightarrow 4$	

directed edges



DAG



topological order

# Depth-first search order

```
public class DepthFirstOrder
{
    private boolean[] marked;
    private Stack<Integer> reversePost;

    public DepthFirstOrder(Digraph G)
    {
        reversePost = new Stack<Integer>();
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
            if (!marked[v]) dfs(G, v);
    }

    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
        reversePost.push(v);
    }

    public Iterable<Integer> reversePost()
    { return reversePost; }
}
```

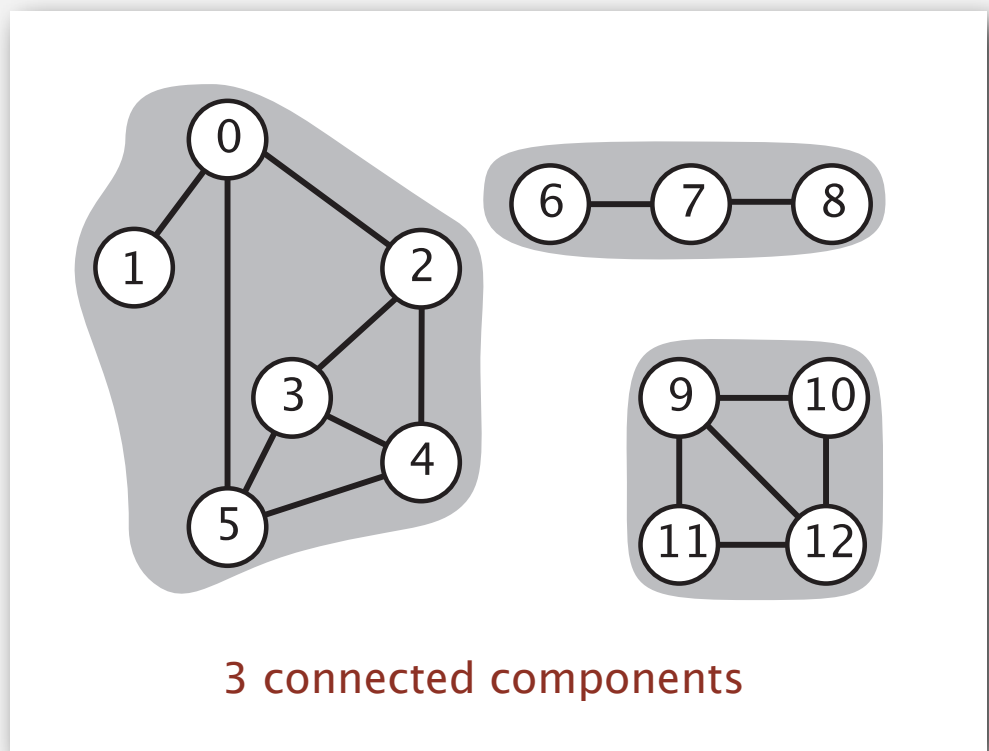
← returns all vertices in  
“reverse DFS postorder”

- ▶ digraph API
- ▶ digraph search
- ▶ topological sort
- ▶ **strong components**

# Connected components vs. strongly-connected components

Analog to connectivity in undirected graphs.

v and w are **connected** if there is a path between v and w



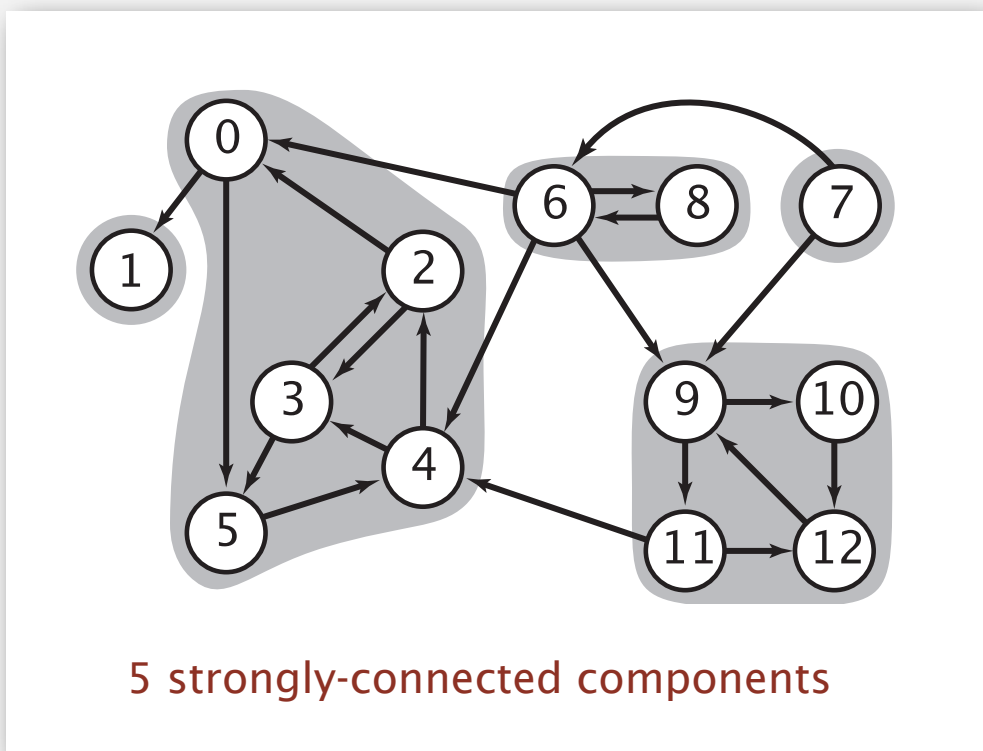
connected component id (easy to compute with DFS)

	0	1	2	3	4	5	6	7	8	9	10	11	12
cc[]	0	0	0	0	0	0	1	1	1	2	2	2	2

```
public int connected(int v, int w)
{ return cc[v] == cc[w]; }
```

constant-time client connectivity query

v and w are **strongly connected** if there is a directed path from v to w and a directed path from w to v



strongly-connected component id (how to compute?)

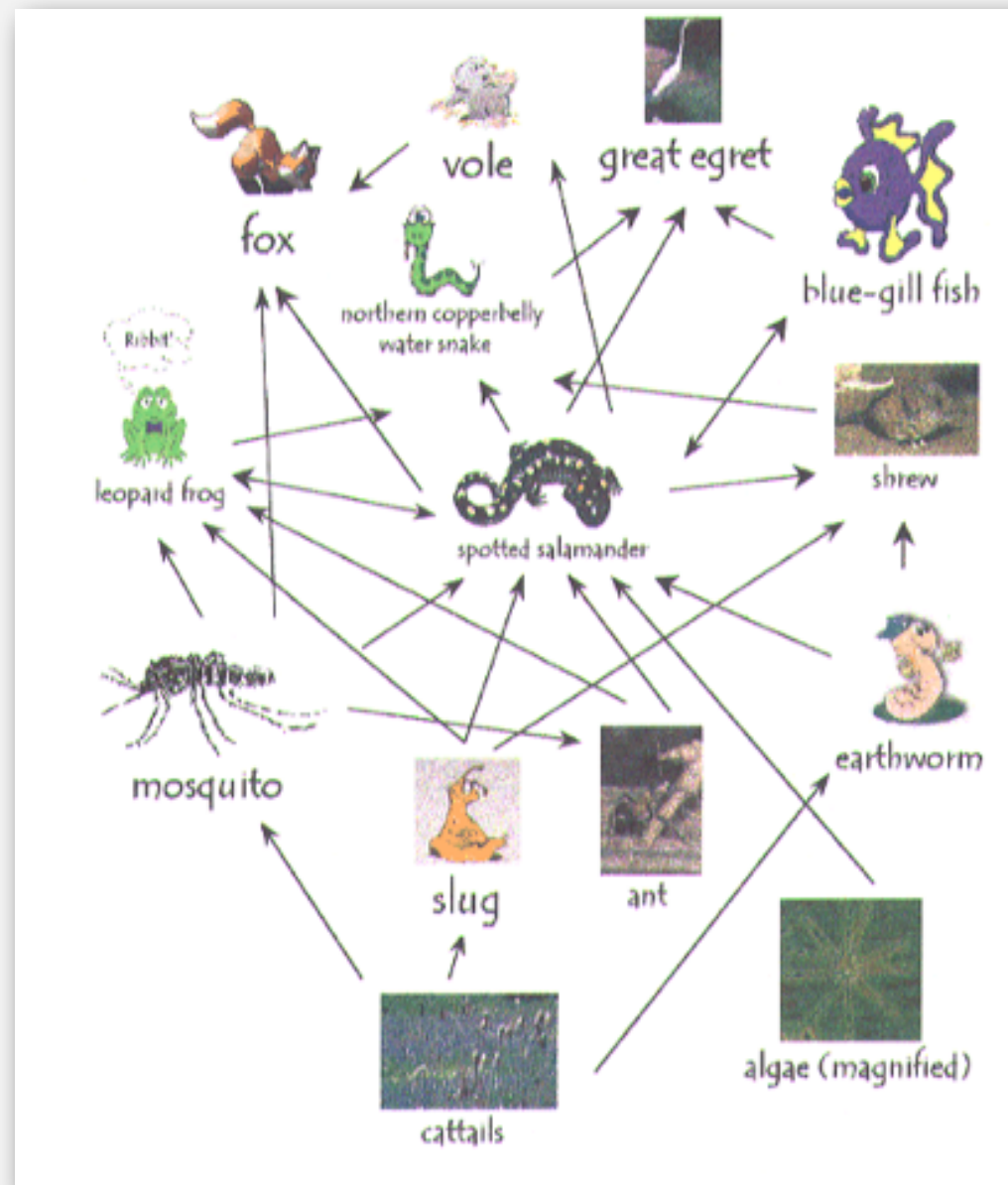
	0	1	2	3	4	5	6	7	8	9	10	11	12
scc[]	1	0	1	1	1	1	3	4	3	2	2	2	2

```
public int stronglyConnected(int v, int w)
{ return scc[v] == scc[w]; }
```

constant-time client strong-connectivity query

# Strong component application: ecological food webs

Food web graph. Vertex = species; edge = from producer to consumer.



<http://www.twingroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.gif>

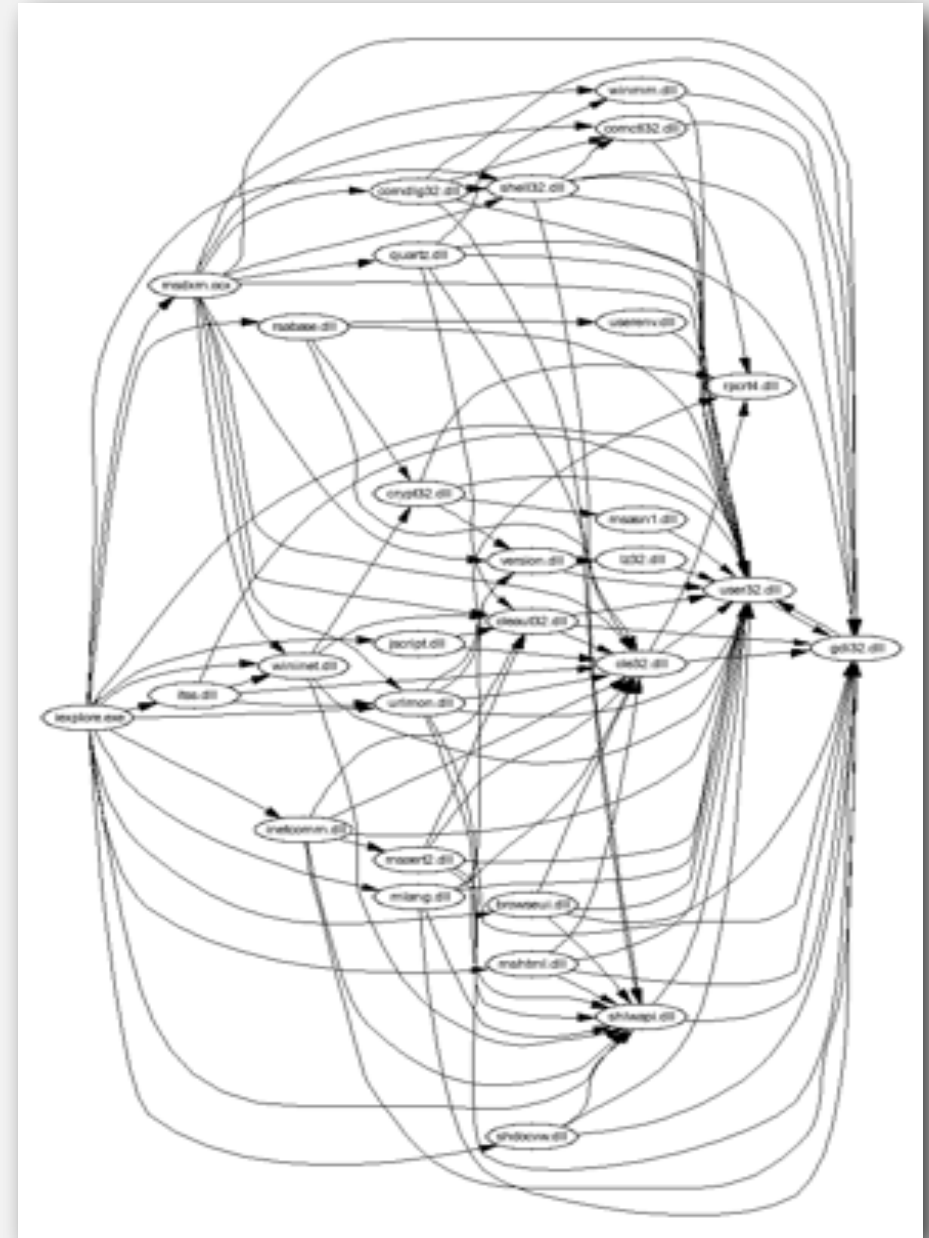
## Strong component application: software modules

# Software module dependency graph.

- Vertex = software module.
- Edge: from module to dependency.



## Firefox



## Internet Explorer

**Strong component.** Subset of mutually interacting modules.

## Approach 1. Package strong components together.



# Strong components algorithms: brief history

1960s: Core OR problem.

- Widely studied; some practical algorithms.
- Complexity not understood.

1972: linear-time DFS algorithm (Tarjan).

- Classic algorithm.
- Level of difficulty: Algs4++.
- Demonstrated broad applicability and importance of DFS.

1980s: easy two-pass linear-time algorithm (Kosaraju-Sharir).

- Forgot notes for lecture; developed algorithm in order to teach it!
- Later found in Russian scientific literature (1972).

1990s: more easy linear-time algorithms.

- Gabow: fixed old OR algorithm.
- Cheriyan-Mehlhorn: needed one-pass algorithm for LEDA.

# Kosaraju's algorithm: intuition

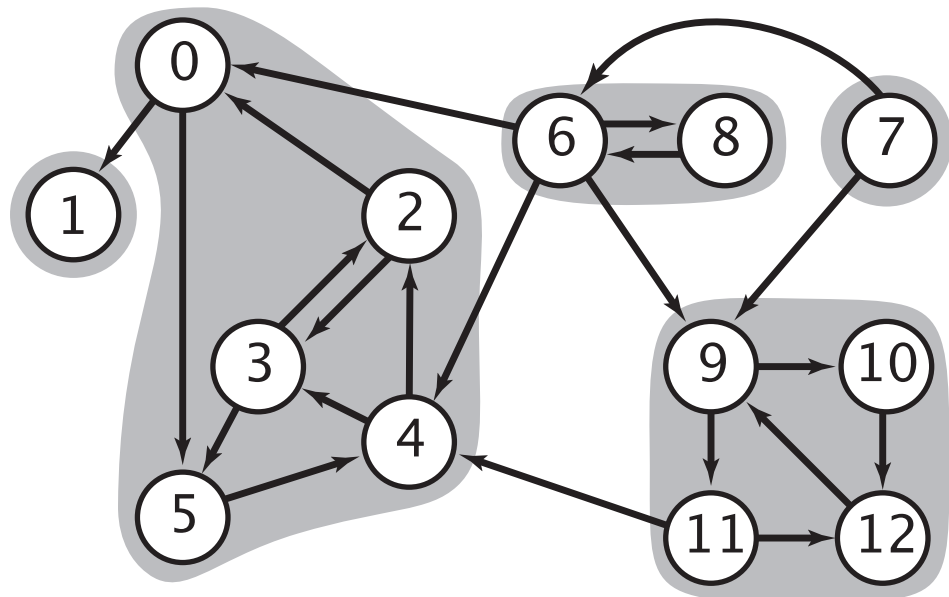
**Reverse graph.** Strong components in  $G$  are same as in  $G^R$ .

**Kernel DAG.** Contract each strong component into a single vertex.

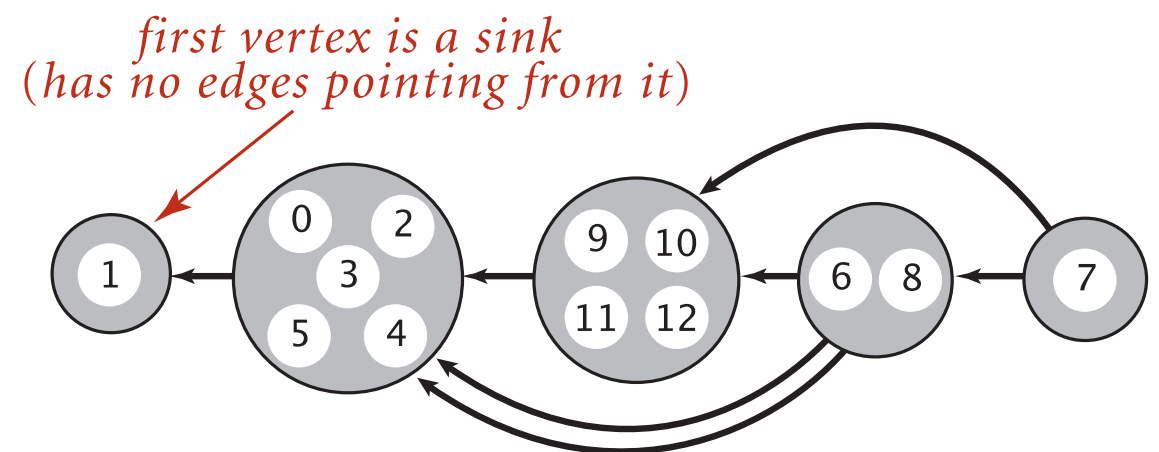
**Idea.**

- Compute topological order (reverse postorder) in kernel DAG.
- Run DFS, considering vertices in reverse topological order.

how to compute?  
↙



digraph  $G$  and its strong components



kernel DAG of  $G$  (in reverse topological order)